

Minmax Methods for Geodesics and Minimal Surfaces

Tristan Rivière

ETH Zürich

Lecture 1 : The Origin of Minmax,
Birkhoff Curve Shortening Process
and its Generalization to Surfaces

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m .

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$.

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s \vec{\gamma}|_{s=0}$

$$\left. \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \right|_{s=0}$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s \vec{\gamma}|_{s=0}$

$$\frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} = \int_{S^1} \partial_s dl_{\vec{\gamma}_s}$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s\vec{\gamma}|_{s=0}$

$$\frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} = \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta}\vec{\gamma} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|} d\theta$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s\vec{\gamma}|_{s=0}$

$$\begin{aligned} \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} &= \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta}\vec{\gamma} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|} d\theta \\ &= \int_{S^1} \partial_{\theta}\vec{w} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|^2} dl_{\vec{\gamma}} \end{aligned}$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s\vec{\gamma}|_{s=0}$

$$\begin{aligned} \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} &= \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta}\vec{\gamma} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|} d\theta \\ &= \int_{S^1} \partial_{\theta}\vec{w} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|^2} dl_{\vec{\gamma}} = \int_{S^1} \langle \nabla\vec{w}, d\vec{\gamma} \rangle_{g_{\vec{\gamma}}} dl_{\vec{\gamma}} \end{aligned}$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s\vec{\gamma}|_{s=0}$

$$\begin{aligned} \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} &= \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta}\vec{\gamma} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|} d\theta \\ &= \int_{S^1} \partial_{\theta}\vec{w} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|^2} dl_{\vec{\gamma}} = \int_{S^1} \langle \nabla\vec{w}, d\vec{\gamma} \rangle_{g_{\vec{\gamma}}} dl_{\vec{\gamma}} \end{aligned}$$

In **normal parametrization** (i.e. $|\partial_{\theta}\vec{\gamma}| \equiv Cte$), the immersion $\vec{\gamma}$ is a critical point of the length if and only if

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s \vec{\gamma}|_{s=0}$

$$\begin{aligned} \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} &= \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta} \vec{\gamma} \cdot \frac{\partial_{\theta} \vec{\gamma}}{|\partial_{\theta} \vec{\gamma}|} d\theta \\ &= \int_{S^1} \partial_{\theta} \vec{w} \cdot \frac{\partial_{\theta} \vec{\gamma}}{|\partial_{\theta} \vec{\gamma}|^2} dl_{\vec{\gamma}} = \int_{S^1} \langle \nabla \vec{w}, d\vec{\gamma} \rangle_{g_{\vec{\gamma}}} dl_{\vec{\gamma}} \end{aligned}$$

In **normal parametrization** (i.e. $|\partial_{\theta}\vec{\gamma}| \equiv Cte$), the immersion $\vec{\gamma}$ is a critical point of the length if and only if

$$\forall \vec{w} \in T_{\vec{\gamma}} N^n \quad \int_{S^1} \partial_{\theta} \vec{w} \cdot \partial_{\theta} \vec{\gamma} d\theta = 0$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s\vec{\gamma}|_{s=0}$

$$\begin{aligned} \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} &= \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta}\vec{\gamma} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|} d\theta \\ &= \int_{S^1} \partial_{\theta}\vec{w} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|^2} dl_{\vec{\gamma}} = \int_{S^1} \langle \nabla\vec{w}, d\vec{\gamma} \rangle_{g_{\vec{\gamma}}} dl_{\vec{\gamma}} \end{aligned}$$

In **normal parametrization** (i.e. $|\partial_{\theta}\vec{\gamma}| \equiv Cte$), the immersion $\vec{\gamma}$ is a critical point of the length if and only if

$$\forall \vec{w} \in T_{\vec{\gamma}}N^n \quad \int_{S^1} \partial_{\theta}\vec{w} \cdot \partial_{\theta}\vec{\gamma} d\theta = 0 \quad \iff \quad P_{\vec{\gamma}}^T (\partial_{\theta^2}^2 \vec{\gamma}) = 0$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s\vec{\gamma}|_{s=0}$

$$\begin{aligned} \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} &= \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta}\vec{\gamma} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|} d\theta \\ &= \int_{S^1} \partial_{\theta}\vec{w} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|^2} dl_{\vec{\gamma}} = \int_{S^1} \langle \nabla\vec{w}, d\vec{\gamma} \rangle_{g_{\vec{\gamma}}} dl_{\vec{\gamma}} \end{aligned}$$

In **normal parametrization** (i.e. $|\partial_{\theta}\vec{\gamma}| \equiv Cte$), the immersion $\vec{\gamma}$ is a critical point of the length if and only if

$$\forall \vec{w} \in T_{\vec{\gamma}}N^n \quad \int_{S^1} \partial_{\theta}\vec{w} \cdot \partial_{\theta}\vec{\gamma} d\theta = 0 \quad \iff \quad P_{\vec{\gamma}}^T (\partial_{\theta^2}^2 \vec{\gamma}) = 0$$

$$\iff \quad \nabla \partial_{\theta}\vec{\gamma} = 0$$

The Equation of Geodesics

N^n closed sub-manifold of \mathbb{R}^m . $\vec{\gamma} : S^1 \rightarrow N^n$

$$L(\vec{\gamma}) := \int_{S^1} dl_{\vec{\gamma}}$$

where $dl_{\vec{\gamma}} := |\partial_{\theta}\vec{\gamma}| d\theta$. Consider $\vec{w} = \partial_s\vec{\gamma}|_{s=0}$

$$\begin{aligned} \frac{d}{ds} \int_{S^1} dl_{\vec{\gamma}_s} \Big|_{s=0} &= \int_{S^1} \partial_s dl_{\vec{\gamma}_s} = \int_{S^1} \partial_s \partial_{\theta}\vec{\gamma} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|} d\theta \\ &= \int_{S^1} \partial_{\theta}\vec{w} \cdot \frac{\partial_{\theta}\vec{\gamma}}{|\partial_{\theta}\vec{\gamma}|^2} dl_{\vec{\gamma}} = \int_{S^1} \langle \nabla\vec{w}, d\vec{\gamma} \rangle_{g_{\vec{\gamma}}} dl_{\vec{\gamma}} \end{aligned}$$

In **normal parametrization** (i.e. $|\partial_{\theta}\vec{\gamma}| \equiv Cte$), the immersion $\vec{\gamma}$ is a critical point of the length if and only if

$$\forall \vec{w} \in T_{\vec{\gamma}}N^n \quad \int_{S^1} \partial_{\theta}\vec{w} \cdot \partial_{\theta}\vec{\gamma} d\theta = 0 \quad \iff \quad P_{\vec{\gamma}}^T (\partial_{\theta^2}^2 \vec{\gamma}) = 0$$

$$\iff \quad \nabla \partial_{\theta}\vec{\gamma} = 0 \quad \iff \quad -\partial_{\theta^2}^2 \vec{\gamma} + \partial_{\theta}(P_{\vec{\gamma}}^T) \partial_{\theta}\vec{\gamma} = 0$$

The Search of Closed Geodesics : $\pi_1(N^n) \neq 0$.

The Search of Closed Geodesics : $\pi_1(N^n) \neq 0$.

Theorem [Hadamard 1898, Poincaré 1905, Cartan 1927]

Assume $\pi_1(N^n) \neq 0$ and let $\alpha \in \pi_1(N^n)$ with $\alpha \neq 0$ then α is realized by a closed geodesic.

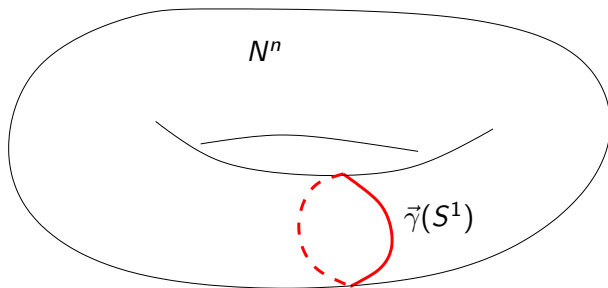


The Search of Closed Geodesics : $\pi_1(N^n) \neq 0$.

Theorem [Hadamard 1898, Poincaré 1905, Cartan 1927]

Assume $\pi_1(N^n) \neq 0$ and let $\alpha \in \pi_1(N^n)$ with $\alpha \neq 0$ then α is realized by a closed geodesic.

□



Proof.

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Observe

$$L^2(\vec{\gamma}) \leq 2\pi E(\vec{\gamma})$$

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Observe

$$L^2(\vec{\gamma}) \leq 2\pi E(\vec{\gamma})$$

Recall

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Observe

$$L^2(\vec{\gamma}) \leq 2\pi E(\vec{\gamma})$$

Recall

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

Arzelà Ascoli \implies

$$\vec{\gamma}_{k'} \rightarrow \vec{\gamma}_\infty \quad \text{strongly in } C^0$$

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Observe

$$L^2(\vec{\gamma}) \leq 2\pi E(\vec{\gamma})$$

Recall

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

Arzelà Ascoli \implies

$$\vec{\gamma}_{k'} \rightarrow \vec{\gamma}_\infty \quad \text{strongly in } C^0$$

Observe

$$\exists \rho > 0 \quad \text{s.t.} \quad \forall z \in N^n \quad B_\delta^{N^n}(z) \text{ is convex.}$$

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Observe

$$L^2(\vec{\gamma}) \leq 2\pi E(\vec{\gamma})$$

Recall

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

Arzelà Ascoli \implies

$$\vec{\gamma}_{k'} \rightarrow \vec{\gamma}_\infty \quad \text{strongly in } C^0$$

Observe

$$\exists \rho > 0 \quad \text{s.t.} \quad \forall z \in N^n \quad B_\delta^{N^n}(z) \text{ is convex.}$$

Connect $\vec{\gamma}_{k'}(\theta)$ and $\vec{\gamma}_\infty(\theta)$ with the unique geodesic in $B_\delta^{N^n}(\vec{\gamma}_\infty(\theta))$.

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Observe

$$L^2(\vec{\gamma}) \leq 2\pi E(\vec{\gamma})$$

Recall

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

Arzelà Ascoli \implies

$$\vec{\gamma}_{k'} \rightarrow \vec{\gamma}_\infty \quad \text{strongly in } C^0$$

Observe

$$\exists \rho > 0 \quad \text{s.t.} \quad \forall z \in N^n \quad B_\delta^{N^n}(z) \text{ is convex.}$$

Connect $\vec{\gamma}_{k'}(\theta)$ and $\vec{\gamma}_\infty(\theta)$ with the unique geodesic in $B_\delta^{N^n}(\vec{\gamma}_\infty(\theta))$. This realizes an **homotopy** between $\vec{\gamma}_{k'}$ and $\vec{\gamma}_\infty$.

Proof. One minimizes

$$E(\vec{\gamma}) := \int_{S^1} \left| \frac{\partial \vec{\gamma}}{\partial \theta} \right|^2 d\theta$$

Observe

$$L^2(\vec{\gamma}) \leq 2\pi E(\vec{\gamma})$$

Recall

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

Arzelà Ascoli \implies

$$\vec{\gamma}_{k'} \rightarrow \vec{\gamma}_\infty \quad \text{strongly in } C^0$$

Observe

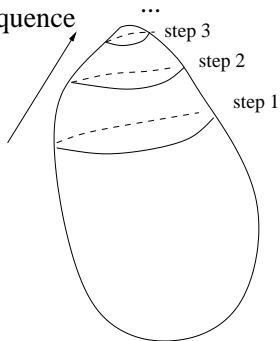
$$\exists \rho > 0 \quad \text{s.t.} \quad \forall z \in N^n \quad B_\delta^{N^n}(z) \text{ is convex.}$$

Connect $\vec{\gamma}_{k'}(\theta)$ and $\vec{\gamma}_\infty(\theta)$ with the unique geodesic in $B_\delta^{N^n}(\vec{\gamma}_\infty(\theta))$. This realizes an **homotopy** between $\vec{\gamma}_{k'}$ and $\vec{\gamma}_\infty$. Hence $[\vec{\gamma}_\infty] = \alpha$.

The case $\pi_1(N^2) = 0$.

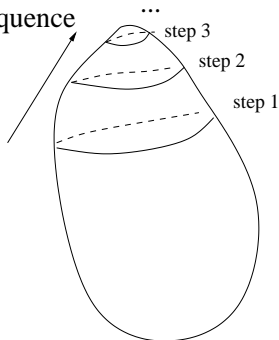
The case $\pi_1(N^2) = 0$.

Vanishing
Minimizing Sequence
of Loops



The case $\pi_1(N^2) = 0$.

Vanishing
Minimizing Sequence
of Loops



The minimization procedure vanishes...

The case $\pi_1(N^2) = 0$.

The case $\pi_1(N^2) = 0$.

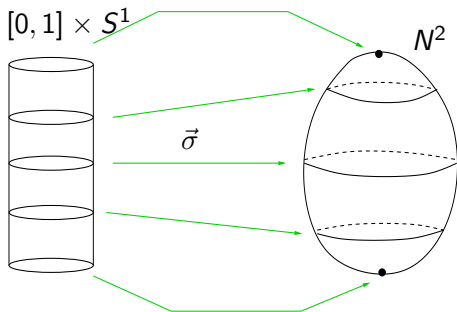
Birkhoff 1917. **sweepouts** of N^2 : $\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$ s.t.

$\vec{\sigma}([0, 1] \times S^1)$ generates $H_2(N^2, \mathbb{Z})$

The case $\pi_1(N^2) = 0$.

Birkhoff 1917. **sweepouts** of N^2 : $\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$ s.t.

$\vec{\sigma}([0, 1] \times S^1)$ generates $H_2(N^2, \mathbb{Z})$



The Notion of Width.

The Notion of Width.

A **sweep-out** is a map $\vec{\sigma} : [0, 1] \times S^1 \rightarrow N^2$ such that

i)

$$\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$$

The Notion of Width.

A **sweep-out** is a map $\vec{\sigma} : [0, 1] \times S^1 \rightarrow N^2$ such that

i)

$$\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$$

ii) $\vec{\sigma}(0, \cdot)$ and $\vec{\sigma}(1, \cdot)$ are constant maps.

The Notion of Width.

A **sweep-out** is a map $\vec{\sigma} : [0, 1] \times S^1 \rightarrow N^2$ such that

i)

$$\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$$

ii) $\vec{\sigma}(0, \cdot)$ and $\vec{\sigma}(1, \cdot)$ are constant maps.

For any $\vec{\sigma}_0 \in \Omega$ define

$$\Omega_{\vec{\sigma}_0} := \{\vec{\sigma} \in \Omega \text{ such that } \vec{\sigma} \text{ and } \vec{\sigma}_0 \text{ are homotopic to each other in } \Omega\}$$

The Notion of Width.

A **sweep-out** is a map $\vec{\sigma} : [0, 1] \times S^1 \rightarrow N^2$ such that

i)

$$\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$$

ii) $\vec{\sigma}(0, \cdot)$ and $\vec{\sigma}(1, \cdot)$ are constant maps.

For any $\vec{\sigma}_0 \in \Omega$ define

$$\Omega_{\vec{\sigma}_0} := \{\vec{\sigma} \in \Omega \text{ such that } \vec{\sigma} \text{ and } \vec{\sigma}_0 \text{ are homotopic to each other in } \Omega\}$$

For any $\vec{\sigma}_0 \in \Omega$ we define the **width** associated to $\vec{\sigma}_0$

The Notion of Width.

A **sweep-out** is a map $\vec{\sigma} : [0, 1] \times S^1 \rightarrow N^2$ such that

i)

$$\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$$

ii) $\vec{\sigma}(0, \cdot)$ and $\vec{\sigma}(1, \cdot)$ are constant maps.

For any $\vec{\sigma}_0 \in \Omega$ define

$$\Omega_{\vec{\sigma}_0} := \{\vec{\sigma} \in \Omega \text{ such that } \vec{\sigma} \text{ and } \vec{\sigma}_0 \text{ are homotopic to each other in } \Omega\}$$

For any $\vec{\sigma}_0 \in \Omega$ we define the **width** associated to $\vec{\sigma}_0$

$$W_{\vec{\sigma}_0} := \inf_{\vec{\sigma} \in \Omega_{\vec{\sigma}_0}} \max_{t \in [0, 1]} E(\vec{\sigma}(t, \cdot))$$

The Notion of Width.

A **sweep-out** is a map $\vec{\sigma} : [0, 1] \times S^1 \rightarrow N^2$ such that

i)

$$\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$$

ii) $\vec{\sigma}(0, \cdot)$ and $\vec{\sigma}(1, \cdot)$ are constant maps.

For any $\vec{\sigma}_0 \in \Omega$ define

$$\Omega_{\vec{\sigma}_0} := \{ \vec{\sigma} \in \Omega \text{ such that } \vec{\sigma} \text{ and } \vec{\sigma}_0 \text{ are homotopic to each other in } \Omega \}$$

For any $\vec{\sigma}_0 \in \Omega$ we define the **width** associated to $\vec{\sigma}_0$

$$W_{\vec{\sigma}_0} := \inf_{\vec{\sigma} \in \Omega_{\vec{\sigma}_0}} \max_{t \in [0, 1]} E(\vec{\sigma}(t, \cdot))$$

Lemma For any closed two dimensional manifold N^2 and any sweep-out $\vec{\sigma}_0$ of N^2 , $W_{\vec{\sigma}_0} > 0$ if and only if $\vec{\sigma}_0$ defines a non zero element of $H_2(N^2)$. □

The Notion of Width.

A **sweep-out** is a map $\vec{\sigma} : [0, 1] \times S^1 \rightarrow N^2$ such that

i)

$$\vec{\sigma} \in C^0([0, 1], W^{1,2}(S^1, N^2))$$

ii) $\vec{\sigma}(0, \cdot)$ and $\vec{\sigma}(1, \cdot)$ are constant maps.

For any $\vec{\sigma}_0 \in \Omega$ define

$$\Omega_{\vec{\sigma}_0} := \{ \vec{\sigma} \in \Omega \text{ such that } \vec{\sigma} \text{ and } \vec{\sigma}_0 \text{ are homotopic to each other in } \Omega \}$$

For any $\vec{\sigma}_0 \in \Omega$ we define the **width** associated to $\vec{\sigma}_0$

$$W_{\vec{\sigma}_0} := \inf_{\vec{\sigma} \in \Omega_{\vec{\sigma}_0}} \max_{t \in [0, 1]} E(\vec{\sigma}(t, \cdot))$$

Lemma For any closed two dimensional manifold N^2 and any sweep-out $\vec{\sigma}_0$ of N^2 , $W_{\vec{\sigma}_0} > 0$ if and only if $\vec{\sigma}_0$ defines a non zero element of $H_2(N^2)$. □

Proof

Proof

Assume $W_{\vec{\sigma}_0} = 0$.

Proof

Assume $W_{\vec{\sigma}_0} = 0$. Let $\vec{\sigma}_k$ be a minimizing sequence :

$$\lim_{k \rightarrow \infty} \max_{t \in [0,1]} E(\vec{\sigma}_k(t, \cdot)) = 0$$

Proof

Assume $W_{\vec{\sigma}_0} = 0$. Let $\vec{\sigma}_k$ be a minimizing sequence :

$$\lim_{k \rightarrow \infty} \max_{t \in [0,1]} E(\vec{\sigma}_k(t, \cdot)) = 0$$

Use again

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

Proof

Assume $W_{\vec{\sigma}_0} = 0$. Let $\vec{\sigma}_k$ be a minimizing sequence :

$$\lim_{k \rightarrow 0} \max_{t \in [0,1]} E(\vec{\sigma}_k(t, \cdot)) = 0$$

Use again

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

For k large enough

$$\forall t \in [0, 1] \quad \vec{\sigma}_k(t, S^1) \subset B_\delta^{N^n}(p_k(t)) \quad \text{convex}$$

where $p_k(t) \in C^0([0, 1], N^n)$.

Proof

Assume $W_{\vec{\sigma}_0} = 0$. Let $\vec{\sigma}_k$ be a minimizing sequence :

$$\lim_{k \rightarrow 0} \max_{t \in [0,1]} E(\vec{\sigma}_k(t, \cdot)) = 0$$

Use again

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

For k large enough

$$\forall t \in [0, 1] \quad \vec{\sigma}_k(t, S^1) \subset B_\delta^{N^n}(p_k(t)) \quad \text{convex}$$

where $p_k(t) \in C^0([0, 1], N^n)$. Using shortest geodesic

homotop $\vec{\sigma}(t, \cdot)$ to the constant map $p_k(t)$

Proof

Assume $W_{\vec{\sigma}_0} = 0$. Let $\vec{\sigma}_k$ be a minimizing sequence :

$$\lim_{k \rightarrow 0} \max_{t \in [0,1]} E(\vec{\sigma}_k(t, \cdot)) = 0$$

Use again

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

For k large enough

$$\forall t \in [0, 1] \quad \vec{\sigma}_k(t, S^1) \subset B_\delta^{N^n}(p_k(t)) \quad \text{convex}$$

where $p_k(t) \in C^0([0, 1], N^n)$. Using shortest geodesic

homotop $\vec{\sigma}(t, \cdot)$ to the constant map $p_k(t)$

Observe

$p_k([0, 1])$ is contractible.

Proof

Assume $W_{\vec{\sigma}_0} = 0$. Let $\vec{\sigma}_k$ be a minimizing sequence :

$$\lim_{k \rightarrow 0} \max_{t \in [0,1]} E(\vec{\sigma}_k(t, \cdot)) = 0$$

Use again

$$W^{1,2}(S^1) \hookrightarrow C^{0,1/2}(S^1)$$

For k large enough

$$\forall t \in [0, 1] \quad \vec{\sigma}_k(t, S^1) \subset B_\delta^{N^n}(p_k(t)) \quad \text{convex}$$

where $p_k(t) \in C^0([0, 1], N^n)$. Using shortest geodesic

homotop $\vec{\sigma}(t, \cdot)$ to the constant map $p_k(t)$

Observe

$p_k([0, 1])$ is contractible.

Hence $[\vec{\sigma}_k([0, 1] \times S^1)] = 0$ in $H_2(N^2)$.



Piecewise Linear Maps with Q Breaks.

Piecewise Linear Maps with Q Breaks.

From now on we assume $W_{\vec{\sigma}_0} > 0$

Piecewise Linear Maps with Q Breaks.

From now on we assume $W_{\vec{\sigma}_0} > 0$ and ask

Does there exist a geodesic $\vec{\gamma}$ such that $L(\vec{\gamma}) = \sqrt{2\pi W_{\vec{\sigma}_0}}$?

Piecewise Linear Maps with Q Breaks.

From now on we assume $W_{\vec{\sigma}_0} > 0$ and ask

Does there exist a geodesic $\vec{\gamma}$ such that $L(\vec{\gamma}) = \sqrt{2\pi W_{\vec{\sigma}_0}}$?

We “project” the space of paths into an “almost finite dimensional space”

Piecewise Linear Maps with Q Breaks.

From now on we assume $W_{\vec{\sigma}_0} > 0$ and ask

Does there exist a geodesic $\vec{\gamma}$ such that $L(\vec{\gamma}) = \sqrt{2\pi W_{\vec{\sigma}_0}}$?

We “project” the space of paths into an “almost finite dimensional space” : Introduce

$$\Lambda^Q := \left\{ \begin{array}{l} \vec{\gamma} \in W^{1,2}(S^1, N^2) \quad \text{s.t.} \quad L(\vec{\gamma}) \leq Q \delta \\ \exists p_0 \leq p_1 \leq \dots \leq p_Q = p_0 \in S^1 \quad \text{s.t.} \quad L([p_i, p_{i+1}]) \leq \delta \\ \nabla^h \partial_\theta \vec{\gamma} = 0 \quad \text{and} \quad |\partial_\theta \vec{\gamma}|(\theta) \equiv Cte \quad \text{on} \quad (p_i, p_{i+1}) \end{array} \right\}$$

Piecewise Linear Maps with Q Breaks.

From now on we assume $W_{\vec{\sigma}_0} > 0$ and ask

Does there exist a geodesic $\vec{\gamma}$ such that $L(\vec{\gamma}) = \sqrt{2\pi W_{\vec{\sigma}_0}}$?

We “project” the space of paths into an “almost finite dimensional space” : Introduce

$$\Lambda^Q := \left\{ \begin{array}{l} \vec{\gamma} \in W^{1,2}(S^1, N^2) \quad \text{s.t. } L(\vec{\gamma}) \leq Q\delta \\ \exists p_0 \leq p_1 \leq \dots \leq p_Q = p_0 \in S^1 \quad \text{s.t. } L([p_i, p_{i+1}]) \leq \delta \\ \nabla^h \partial_\theta \vec{\gamma} = 0 \quad \text{and} \quad |\partial_\theta \vec{\gamma}|(\theta) \equiv \text{Cte} \quad \text{on } (p_i, p_{i+1}) \end{array} \right\}$$

Observe

$$W_{\vec{\sigma}_0} = \inf_{\vec{\sigma} \in \Omega_{\vec{\sigma}_0} \cap \Lambda^Q} \max_{t \in [0,1]} E(\vec{\sigma}(t, \cdot))$$

for some $Q \in \mathbb{N}$.

Piecewise Linear Maps with Q Breaks.

From now on we assume $W_{\vec{\sigma}_0} > 0$ and ask

Does there exist a geodesic $\vec{\gamma}$ such that $L(\vec{\gamma}) = \sqrt{2\pi W_{\vec{\sigma}_0}}$?

We “project” the space of paths into an “almost finite dimensional space” : Introduce

$$\Lambda^Q := \left\{ \begin{array}{l} \vec{\gamma} \in W^{1,2}(S^1, N^2) \quad \text{s.t. } L(\vec{\gamma}) \leq Q\delta \\ \exists p_0 \leq p_1 \leq \dots \leq p_Q = p_0 \in S^1 \quad \text{s.t. } L([p_i, p_{i+1}]) \leq \delta \\ \nabla^h \partial_\theta \vec{\gamma} = 0 \quad \text{and} \quad |\partial_\theta \vec{\gamma}|(\theta) \equiv \text{Cte} \quad \text{on } (p_i, p_{i+1}) \end{array} \right\}$$

Observe

$$W_{\vec{\sigma}_0} = \inf_{\vec{\sigma} \in \Omega_{\vec{\sigma}_0} \cap \Lambda^Q} \max_{t \in [0,1]} E(\vec{\sigma}(t, \cdot))$$

for some $Q \in \mathbb{N}$. Denote

$$G := \Lambda \cap \{\text{immersed closed geodesics}\}$$

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Theorem [Birkhoff 1918] \exists a morphism $\Psi : \Lambda \longrightarrow \Lambda$ s.t.

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Theorem [Birkhoff 1918] \exists a morphism $\Psi : \Lambda \longrightarrow \Lambda$ s.t.

i) Ψ is continuous (Λ is equipped with the $W^{1,2}$ topology.)

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Theorem [Birkhoff 1918] \exists a morphism $\Psi : \Lambda \longrightarrow \Lambda$ s.t.

- i) Ψ is continuous (Λ is equipped with the $W^{1,2}$ topology.)
- ii) $\forall \vec{\sigma} \in \Lambda$, $\Psi(\vec{\sigma})$ is homotopic to $\vec{\sigma}$,

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Theorem [Birkhoff 1918] \exists a morphism $\Psi : \Lambda \longrightarrow \Lambda$ s.t.

- i) Ψ is continuous (Λ is equipped with the $W^{1,2}$ topology.)
- ii) $\forall \vec{\sigma} \in \Lambda$, $\Psi(\vec{\sigma})$ is homotopic to $\vec{\sigma}$,
- iii) $\forall \vec{\sigma} \in \Lambda$,

$$L(\Psi(\vec{\sigma})) \leq L(\vec{\sigma}) \quad ,$$

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Theorem [Birkhoff 1918] \exists a morphism $\Psi : \Lambda \longrightarrow \Lambda$ s.t.

- i) Ψ is continuous (Λ is equipped with the $W^{1,2}$ topology.)
- ii) $\forall \vec{\sigma} \in \Lambda$, $\Psi(\vec{\sigma})$ is homotopic to $\vec{\sigma}$,
- iii) $\forall \vec{\sigma} \in \Lambda$,

$$L(\Psi(\vec{\sigma})) \leq L(\vec{\sigma}) \quad ,$$

- iv) $\exists \varphi \in C^0([0, \infty), [0, \infty))$ s.t. $\varphi(0) = 0$ and

$$\text{dist}^2(\vec{\sigma}, \Psi(\vec{\sigma})) \leq \varphi\left(\frac{L^2(\vec{\sigma}) - L^2(\Psi(\vec{\sigma}))}{L^2(\Psi(\vec{\sigma}))}\right)$$

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Theorem [Birkhoff 1918] \exists a morphism $\Psi : \Lambda \longrightarrow \Lambda$ s.t.

- i) Ψ is continuous (Λ is equipped with the $W^{1,2}$ topology.)
- ii) $\forall \vec{\sigma} \in \Lambda$, $\Psi(\vec{\sigma})$ is homotopic to $\vec{\sigma}$,
- iii) $\forall \vec{\sigma} \in \Lambda$,

$$L(\Psi(\vec{\sigma})) \leq L(\vec{\sigma}) \quad ,$$

- iv) $\exists \varphi \in C^0([0, \infty), [0, \infty))$ s.t. $\varphi(0) = 0$ and

$$\text{dist}^2(\vec{\sigma}, \Psi(\vec{\sigma})) \leq \varphi\left(\frac{L^2(\vec{\sigma}) - L^2(\Psi(\vec{\sigma}))}{L^2(\Psi(\vec{\sigma}))}\right)$$

- v) $\forall \varepsilon > 0 \quad \exists \alpha > 0$ s.t.

$$\text{dist}(\vec{\sigma}, G) \geq \varepsilon \quad \implies \quad L(\Psi(\vec{\sigma})) \leq L(\vec{\sigma}) - \alpha \quad .$$

Birkhoff Curve Shortening Map : The “Prehistory” of Pseudo-Gradient Flows.

Theorem [Birkhoff 1918] \exists a morphism $\Psi : \Lambda \rightarrow \Lambda$ s.t.

- i) Ψ is continuous (Λ is equipped with the $W^{1,2}$ topology.)
- ii) $\forall \vec{\sigma} \in \Lambda$, $\Psi(\vec{\sigma})$ is homotopic to $\vec{\sigma}$,
- iii) $\forall \vec{\sigma} \in \Lambda$,


$$L(\Psi(\vec{\sigma})) \leq L(\vec{\sigma}) \quad ,$$

- iv) $\exists \varphi \in C^0([0, \infty), [0, \infty))$ s.t. $\varphi(0) = 0$ and

$$\text{dist}^2(\vec{\sigma}, \Psi(\vec{\sigma})) \leq \varphi\left(\frac{L^2(\vec{\sigma}) - L^2(\Psi(\vec{\sigma}))}{L^2(\Psi(\vec{\sigma}))}\right)$$

- v) $\forall \varepsilon > 0 \quad \exists \alpha > 0$ s.t.

$$\text{dist}(\vec{\sigma}, G) \geq \varepsilon \quad \implies \quad L(\Psi(\vec{\sigma})) \leq L(\vec{\sigma}) - \alpha \quad .$$

where the distance is derived from the $W^{1,2}$ norm. 

Existence of Closed Geodesics Realizing $W_{\vec{\sigma}_0} > 0$.

Existence of Closed Geodesics Realizing $W_{\vec{\sigma}_0} > 0$.

Theorem *Let $\vec{\sigma}_0$ be a sweepout of N^2 such that $W_{\vec{\sigma}_0} > 0$ then the number $W_{\vec{\sigma}_0}$ is the length of a closed geodesics in N^2 homotopic to $\vec{\sigma}_0$. □*

Existence of Closed Geodesics Realizing $W_{\vec{\sigma}_0} > 0$.

Theorem *Let $\vec{\sigma}_0$ be a sweepout of N^2 such that $W_{\vec{\sigma}_0} > 0$ then the number $W_{\vec{\sigma}_0}$ is the length of a closed geodesics in N^2 homotopic to $\vec{\sigma}_0$. □*

Proof :

Existence of Closed Geodesics Realizing $W_{\vec{\sigma}_0} > 0$.

Theorem *Let $\vec{\sigma}_0$ be a sweepout of N^2 such that $W_{\vec{\sigma}_0} > 0$ then the number $W_{\vec{\sigma}_0}$ is the length of a closed geodesic in N^2 homotopic to $\vec{\sigma}_0$. \square*

Proof : We “pull tight” a minimizing sequence $\vec{\sigma}_k$ into $\vec{\gamma}_k = \Psi(\vec{\sigma}_k)$.

Existence of Closed Geodesics Realizing $W_{\vec{\sigma}_0} > 0$.

Theorem *Let $\vec{\sigma}_0$ be a sweepout of N^2 such that $W_{\vec{\sigma}_0} > 0$ then the number $W_{\vec{\sigma}_0}$ is the length of a closed geodesic in N^2 homotopic to $\vec{\sigma}_0$. \square*

Proof : We “pull tight” a minimizing sequence $\vec{\sigma}_k$ into $\vec{\gamma}_k = \Psi(\vec{\sigma}_k)$. Hence

$\forall \varepsilon > 0 \quad \exists \eta > 0 \quad \text{s.t. for } k \text{ large enough}$

$$(2\pi)^{-1} L^2(\vec{\gamma}_k(t, \cdot)) = E(\vec{\gamma}_k(t, \cdot)) \geq W_{\vec{\sigma}_0} - \eta \implies \text{dist}(\vec{\gamma}_k(t, \cdot), G) \leq \varepsilon$$

\square

A Strict Convexity Behind the Construction of Ψ .

A Strict Convexity Behind the Construction of Ψ .

Lemma *Let I be an interval in S^1 such that $|I| \leq \delta/2\pi$*

A Strict Convexity Behind the Construction of Ψ .

Lemma *Let I be an interval in S^1 such that $|I| \leq \delta/2\pi$ and let $\vec{\sigma}_1$ be a Lipschitz map on I such that $|\partial_\theta \vec{\sigma}_1| \leq 1$*

A Strict Convexity Behind the Construction of Ψ .

Lemma *Let I be an interval in S^1 such that $|I| \leq \delta/2\pi$ and let $\vec{\sigma}_1$ be a Lipschitz map on I such that $|\partial_\theta \vec{\sigma}_1| \leq 1$ and $\vec{\sigma}_2$ be the minimizing geodesic with the same end points,*

A Strict Convexity Behind the Construction of Ψ .

Lemma *Let I be an interval in S^1 such that $|I| \leq \delta/2\pi$ and let $\vec{\sigma}_1$ be a Lipschitz map on I such that $|\partial_\theta \vec{\sigma}_1| \leq 1$ and $\vec{\sigma}_2$ be the minimizing geodesic with the same end points, then we have*

$$\text{dist}^2(\vec{\sigma}_1, \vec{\sigma}_2) \leq C [E(\vec{\sigma}_1) - E(\vec{\sigma}_2)]$$

where $C > 0$ only depends on N^n . □

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Sacks-Uhlenbeck 1980 :

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Sacks-Uhlenbeck 1980 : Let $\Gamma \in \pi_2(N^n)$

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Sacks-Uhlenbeck 1980 : Let $\Gamma \in \pi_2(N^n)$

Step 1 : Minimize

$$E_\sigma(u) := \int_{S^2} (1 + |du|_{S^2}^2)^{(1+\sigma)} dvol_{S^2} \quad \text{s.t.} \quad [u] = \Gamma \neq 0$$

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Sacks-Uhlenbeck 1980 : Let $\Gamma \in \pi_2(N^n)$

Step 1 : Minimize

$$E_\sigma(u) := \int_{S^2} (1 + |du|_{S^2}^2)^{(1+\sigma)} dvol_{S^2} \quad \text{s.t.} \quad [u] = \Gamma \neq 0$$

The problem is **sub-critical**.

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Sacks-Uhlenbeck 1980 : Let $\Gamma \in \pi_2(N^n)$

Step 1 : Minimize

$$E_\sigma(u) := \int_{S^2} (1 + |du|_{S^2}^2)^{(1+\sigma)} d\text{vol}_{S^2} \quad \text{s.t.} \quad [u] = \Gamma \neq 0$$

The problem is **sub-critical**.

Step 2 : u_σ be a minimizer. Make $\sigma \rightarrow 0$.

Existence of Minimal Spheres. $\pi_2(N^n) \neq 0$

Sacks-Uhlenbeck 1980 : Let $\Gamma \in \pi_2(N^n)$

Step 1 : Minimize

$$E_\sigma(u) := \int_{S^2} (1 + |du|_{S^2}^2)^{(1+\sigma)} dvol_{S^2} \quad \text{s.t.} \quad [u] = \Gamma \neq 0$$

The problem is **sub-critical**.

Step 2 : u_σ be a minimizer. Make $\sigma \rightarrow 0$.

Lemma. Uniform ϵ -regularity $\exists \epsilon_N > 0$ s.t. $\forall 0 \leq \sigma \leq 1$

$$\int_{B_r(x)} (1 + |du_\sigma|_{S^2}^2)^{(1+\sigma)} dvol_{S^2} < \epsilon_N \implies |du_\sigma|(x) \leq r^{-1}$$

The Origins of Concentration Compactness

The Origins of Concentration Compactness

Uniform ϵ -regularity $\implies u_\sigma \in W^{1,2}$ – *bubble tree converges* towards

$$u^1 \dots u^Q : S^2 \longrightarrow N^n$$

the u^j are *conformal harmonic*

The Origins of Concentration Compactness

Uniform ϵ -regularity $\implies u_\sigma \in W^{1,2}$ – *bubble tree converges* towards

$$u^1 \dots u^Q : S^2 \longrightarrow N^n$$

the u^j are *conformal harmonic* hence $u(S^2)$ are *minimal spheres*

The Origins of Concentration Compactness

Uniform ϵ -regularity $\implies u_\sigma \in W^{1,2}$ – *bubble tree converges* towards

$$u^1 \cdots u^Q : S^2 \longrightarrow N^n$$

the u^j are **conformal harmonic** hence $u(S^2)$ are **minimal spheres**
and

$$[u^1] \oplus \cdots \oplus [u^Q] = \Gamma$$

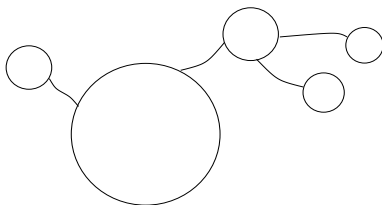
The Origins of Concentration Compactness

Uniform ϵ -regularity $\implies u_\sigma \in W^{1,2}$ - *bubble tree converges* towards

$$u^1 \dots u^Q : S^2 \longrightarrow N^n$$

the u^j are **conformal harmonic** hence $u(S^2)$ are **minimal spheres** and

$$[u^1] \oplus \dots \oplus [u^Q] = \Gamma$$



Bubble Tree of Minimal Spheres

Colding-Minicozzi Min-Max Construction of Minimal Spheres

Colding-Minicozzi Min-Max Construction of Minimal Spheres

Sweepouts of N^3

Colding-Minicozzi Min-Max Construction of Minimal Spheres

Sweepouts of N^3 : $u \in C^0([0, 1], W^{1,2}(S^2, N^3))$ s.t.

$$u([0, 1] \times S^2) \quad \text{generates} \quad H_3(N^3, \mathbb{Z})$$

Colding-Minicozzi Min-Max Construction of Minimal Spheres

Sweepouts of N^3 : $u \in C^0([0, 1], W^{1,2}(S^2, N^3))$ s.t.

$$u([0, 1] \times S^2) \quad \text{generates} \quad H_3(N^3, \mathbb{Z})$$

the following energy level

$$0 < W := \inf_{u(s, \cdot)} \text{sweepout} \max_{s \in [0, 1]} \int_{S^2} |du|_{S^2}^2 d\text{vol}_{S^2}$$

is achieved by a **bubble tree** of **conformal harmonic maps**.

Colding-Minicozzi Min-Max Construction of Minimal Spheres

Sweepouts of N^3 : $u \in C^0([0, 1], W^{1,2}(S^2, N^3))$ s.t.

$$u([0, 1] \times S^2) \quad \text{generates} \quad H_3(N^3, \mathbb{Z})$$

the following energy level

$$0 < W := \inf_{u(s, \cdot) \text{ sweepout}} \max_{s \in [0, 1]} \int_{S^2} |du|_{S^2}^2 \, d\text{vol}_{S^2}$$

is achieved by a **bubble tree** of **conformal harmonic maps**.

The proof is very involved.

Colding-Minicozzi Min-Max Construction of Minimal Spheres

Sweepouts of N^3 : $u \in C^0([0, 1], W^{1,2}(S^2, N^3))$ s.t.

$$u([0, 1] \times S^2) \quad \text{generates} \quad H_3(N^3, \mathbb{Z})$$

the following energy level

$$0 < W := \inf_{u(s, \cdot) \text{ sweepout}} \max_{s \in [0, 1]} \int_{S^2} |du|_{S^2}^2 \, d\text{vol}_{S^2}$$

is achieved by a **bubble tree** of **conformal harmonic maps**.

The proof is very involved. Based on **harmonic replacement** method coming from the **local convexity** of the **harmonic map Lagrangian**.

It replaces Birkhoff **curve shortening** procedure.

Min-Max in Geometric Measure Theory.

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality.

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .)

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .) **Federer, Fleming, De Giorgi, Reifenberg...etc** \simeq 50's

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .) **Federer, Fleming, De Giorgi, Reifenberg...etc** \simeq 50's

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .) **Federer, Fleming, De Giorgi, Reifenberg...etc** \simeq 50's

In a second period GMT has been adapted to **non-minimizing procedures**.

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .) **Federer, Fleming, De Giorgi, Reifenberg...etc** \simeq 50's

In a second period GMT has been adapted to **non-minimizing procedures**. Rectifiable currents are not operative anymore.

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .) **Federer, Fleming, De Giorgi, Reifenberg...etc** \simeq 50's

In a second period GMT has been adapted to **non-minimizing procedures**. Rectifiable currents are not operative anymore. Main Object : **Varifolds** (i.e. Radon Measures on the space of planes)

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .) **Federer, Fleming, De Giorgi, Reifenberg...etc** \simeq 50's

In a second period GMT has been adapted to **non-minimizing procedures**. Rectifiable currents are not operative anymore. Main Object : **Varifolds** (i.e. Radon Measures on the space of planes) **Allard, Almgren, Pitts...etc** \simeq 70-80's

Min-Max in Geometric Measure Theory.

GMT has been introduced to solve the **Plateau Problem** in full generality. Main object : **Rectifiable current** (i.e. Vectorial distribution carried by a “*measure theoretic version of sub-manifold*” .) **Federer, Fleming, De Giorgi, Reifenberg...etc** \simeq 50's

In a second period GMT has been adapted to **non-minimizing procedures**. Rectifiable currents are not operative anymore. Main Object : **Varifolds** (i.e. Radon Measures on the space of planes) **Allard, Almgren, Pitts...etc** \simeq 70-80's

This has brought important results in **codimension 1**.

Existence Result for Non-Minimizing Minimal Surfaces via GMT.

Existence Result for Non-Minimizing Minimal Surfaces via GMT.

Theorem [Almgren, Pitts, Simon, Smith, 1982] Let $3 \leq m \leq 7$ and (M^m, g) be a closed Riemannian manifold then there exists a smooth embedded minimal surface of codimension 1 in M^m . \square

Existence Result for Non-Minimizing Minimal Surfaces via GMT.

Theorem [Almgren, Pitts, Simon, Smith, 1982] Let $3 \leq m \leq 7$ and (M^m, g) be a closed Riemannian manifold then there exists a smooth embedded minimal surface of codimension 1 in M^m . \square

Conjecture [S.T. Yau, 1980] Any compact 3 dimensional Riemannian manifold contains **infinitely many** smooth minimal immersions of closed surfaces. \square

Existence Result for Non-Minimizing Minimal Surfaces via GMT.

Theorem [Almgren, Pitts, Simon, Smith, 1982] Let $3 \leq m \leq 7$ and (M^m, g) be a closed Riemannian manifold then there exists a smooth embedded minimal surface of codimension 1 in M^m . \square

Conjecture [S.T. Yau, 1980] Any compact 3 dimensional Riemannian manifold contains **infinitely many** smooth minimal immersions of closed surfaces. \square

Theorem [Marques, Neves, 2016] Let $3 \leq m \leq 7$ and (M^m, g) be a closed Riemannian manifold of positive Ricci curvature then there exists **infinitely many** embedded minimal surface of codimension 1 in M^m . \square